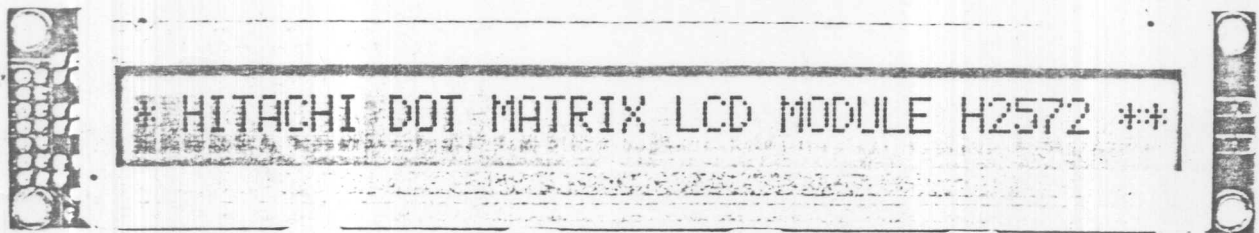


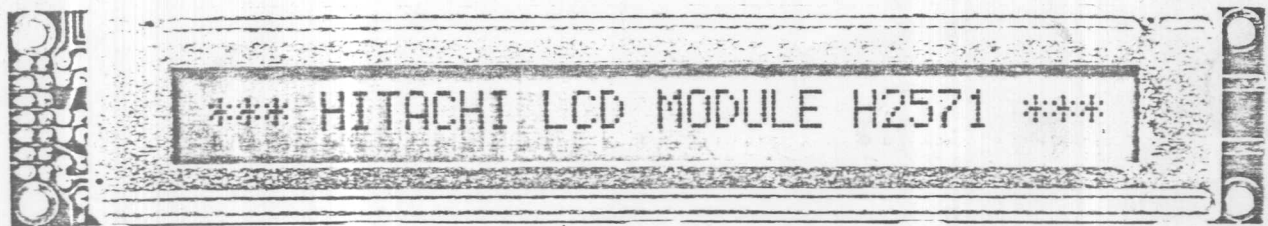
ALPHANUMERIC DOT MATRIX LCD MODULE

H2570 • H2571 • H2572

TENTATIVE DATA



H2572: 40 characters



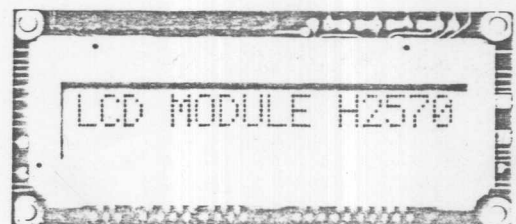
H2571: 32 characters

DESCRIPTION

The H2570, H2571, H2572 are a new line of liquied crystal display modules from Hitachi. These modules utilize 5 x 7 and 5 x 10 dot matrix characters to provide full alphanumeric capability. All control, refresh, and display functions are executed by a dedicated on-board controller. This architecture yields minimum flexibility and very high reliability.

All LCD modules are capable of displaying the full 160-character JIS font set (which includes lower case descenders) plus 32-character special font sets under user software control. The displayed characters are easily readable and gave a contrast ratio that improves as ambient light is increased.

Data interfacing is via an 8-bit bi-directional data bus or a 4-bit one. By use of simple control commands, data can be selectively written to (or read from) any cursor location, arbitrary fonts can be written to CHARACTER GENERATOR RAM, the mode of display function can be determined and so on.



H2570: 16 characters

Note: The information contained herein is tentative and may be changed without prior notice. It is therefore advisable to contact Hitachi before processing with the design of equipment in incorporating this product.

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FEATURES

- 5 x 7 and 5 x 10 dot matrix with cursor
- Single +5 V power supply
- On-board control LSI (HD44780)
- Powerful control commands
 - Display clear
 - Cursor home
 - Display shift
 - Display data read/write etc.
- Microprocessor-compatible data bus interface (8 bit or 4 bit)
- Exceptionally low power consumption
- Extremely compact and light weight

APPLICATIONS

HITACHI Alphanumeric Displays can be used in a wide variety of applications including (but not limited to):

- Portable data terminals
- Handheld computers
- Telephone interconnect equipment
- Text editing devices (e.g. word-processors and typesetters)
- Automated scales and labeling equipment
- Process controllers
- TTY Terminals for the deaf

ABSOLUTE MAXIMUM RATINGS

| Item | Symbol | min. | max. | Unit |
|----------------------------|-----------------|----------|----------|------|
| Power supply for logic | $V_{DD}-V_{SS}$ | 0 | 7.0 | V |
| Power supply for LCD drive | $V_{DD}-V_o$ | 0 | 13.5 | V |
| Input voltage | V_i | V_{SS} | V_{DD} | V |
| Static electricity | — | — | 100 | V |
| Operating temperature | T_a | 0 | 50 | °C |
| Storage temperature | T_{stg} | -20 | 70 | °C |

ELECTRIC CHARACTERISTICS

$T_a = 25^\circ\text{C}$, $V_{DD} = 5.0\text{V} \pm 0.25\text{V}$

| Item | Symbol | Condition | min. | typ. | max. | Unit |
|---|--------------|---------------------------|--------------------------|------|------|------|
| Input "high" voltage | V_{iH} | — | 2.0 | — | — | V |
| Input "low" voltage | V_{iL} | — | — | — | 0.8 | V |
| Output "high" voltage | V_{oH} | $-I_{oH} = 0.2\text{ mA}$ | 2.4 | — | — | V |
| Output "low" voltage | V_{oL} | $I_{oL} = 1.6\text{ mA}$ | — | — | 0.4 | V |
| Power supply current | I_{DD} | $V_{DD} = 5.0\text{ V}$ | — | 0.5 | 2.0 | mA |
| Power supply for LCD drive (Recommended) | $V_{DD}-V_o$ | Duty = 1/11 | $T_a = 0^\circ\text{C}$ | — | 4.2 | V |
| | | | $T_a = 25^\circ\text{C}$ | — | 3.8 | V |
| | | | $T_a = 50^\circ\text{C}$ | — | 3.3 | V |
| | | Duty = 1/8 | $T_a = 0^\circ\text{C}$ | — | 4.0 | V |
| | | | $T_a = 25^\circ\text{C}$ | — | 3.7 | V |
| | | | $T_a = 50^\circ\text{C}$ | — | 3.3 | V |



TIMING CHARACTERISTICS

| Item | Symbol | Test condition | min. | typ. | max. | Unit |
|-----------------------|------------------|----------------|------|------|------|---------|
| Enable cycle time | t_{cyc} | Fig. 1, Fig. 2 | 1.0 | — | — | μ s |
| Enable pulse width | P_{WEH} | Fig. 1, Fig. 2 | 450 | — | — | ns |
| Enable rise/fall time | t_{Er}, t_{Ef} | Fig. 1, Fig. 2 | — | — | 25 | ns |
| RS, R/W set up time | t_{AS} | Fig. 1, Fig. 2 | 140 | — | — | ns |
| Data delay time | t_{DDR} | Fig. 2 | — | — | 300 | ns |
| Data set up time | t_{DSW} | Fig. 1 | 225 | — | — | ns |
| Hold time | t_H | Fig. 1, Fig. 2 | 10 | — | — | ns |

Write operation

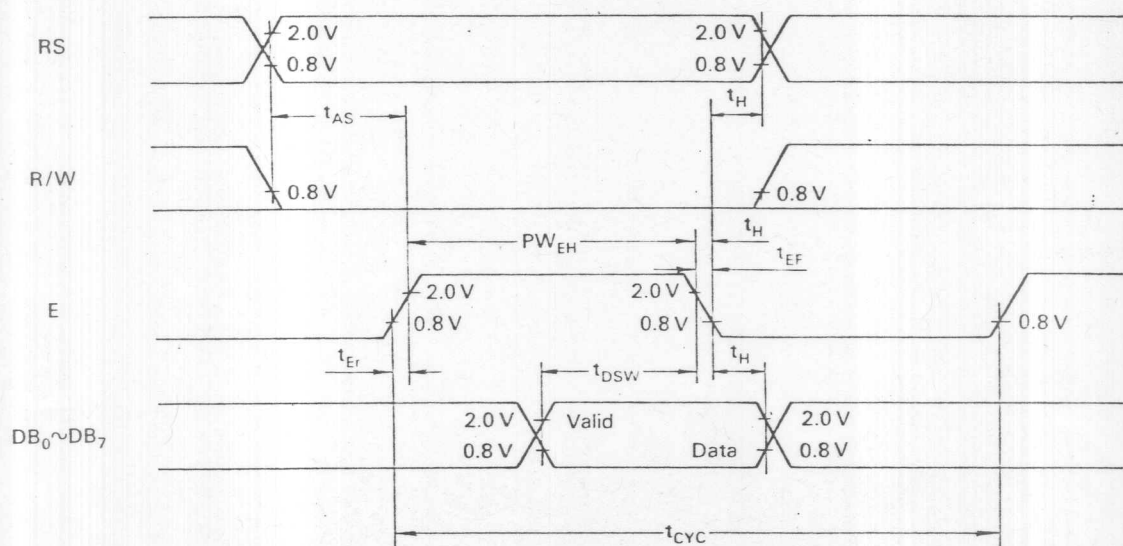


Fig. 1 Interface timing (Data write)

Read operation

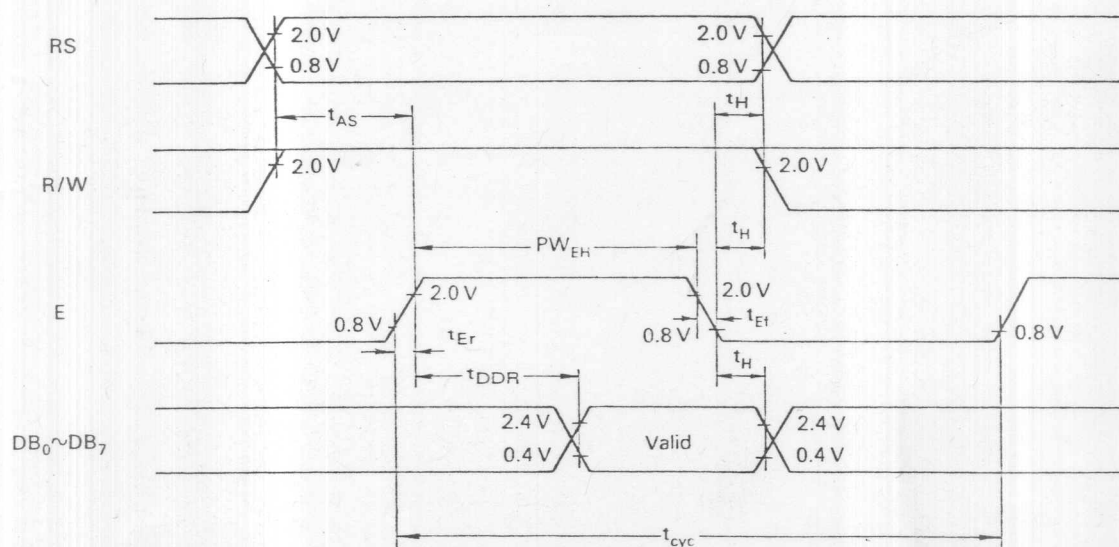
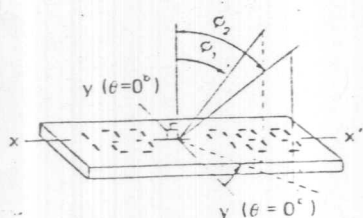


Fig. 2 Interface timing (Data read)

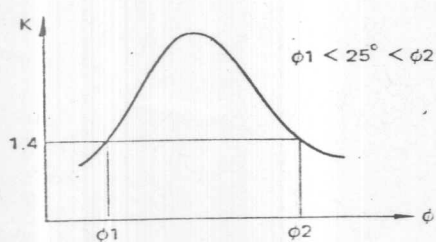


| Item | Symbol | Condition | min. | typ. | max. | Unit | Test |
|----------------------|-------------------|---|------|------|------|------|------|
| Viewing angle | $\phi_2 - \phi_1$ | $K = 1.4$ | 20 | — | — | deg | 1, 2 |
| Contrast ratio | K | $\phi = 25^\circ$ $\theta = 0^\circ$ | 3 | — | — | — | 3 |
| Response time (rise) | t_r | $\phi = 25^\circ$ | — | 150 | 250 | ms | 4 |
| Response time (fall) | t_f | $\phi = 25^\circ$ | — | 150 | 250 | ms | 4 |

Note 1. Definition of θ and ϕ



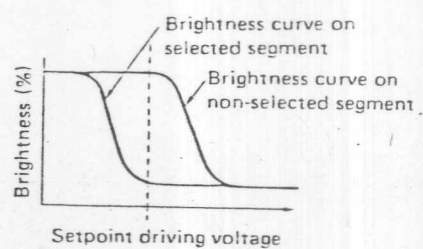
Note 2. Definition of viewing angle ϕ_1 , and ϕ_2 :



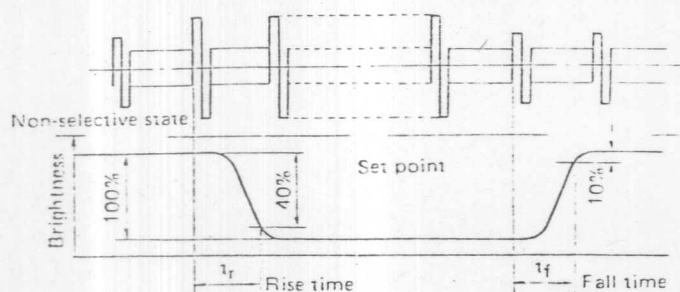
Contrast ratio K vs viewing angle ϕ

Note 3. Definition of contrast "K"

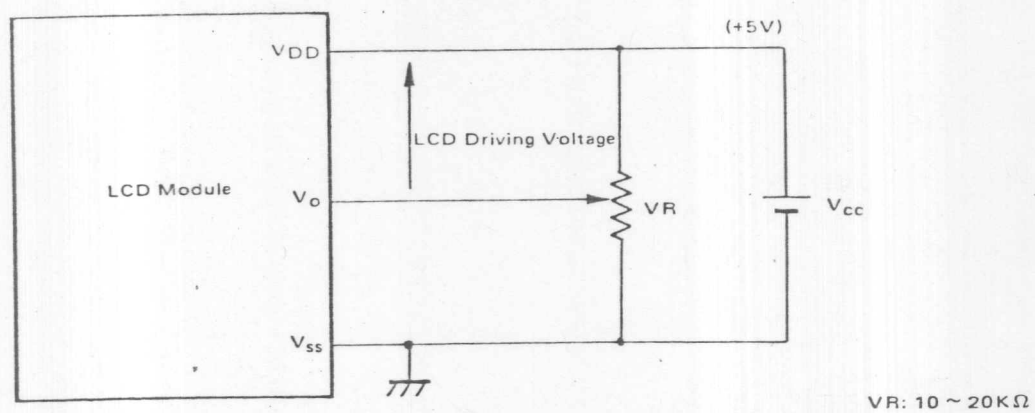
$$K = \frac{\text{Brightness on non-selected segment (B}_2\text{)}}{\text{Brightness on selected segment (B}_1\text{)}}$$



Note 4. Definition of optical response



POWER SUPPLY for LCD MODULE
(Recommended)

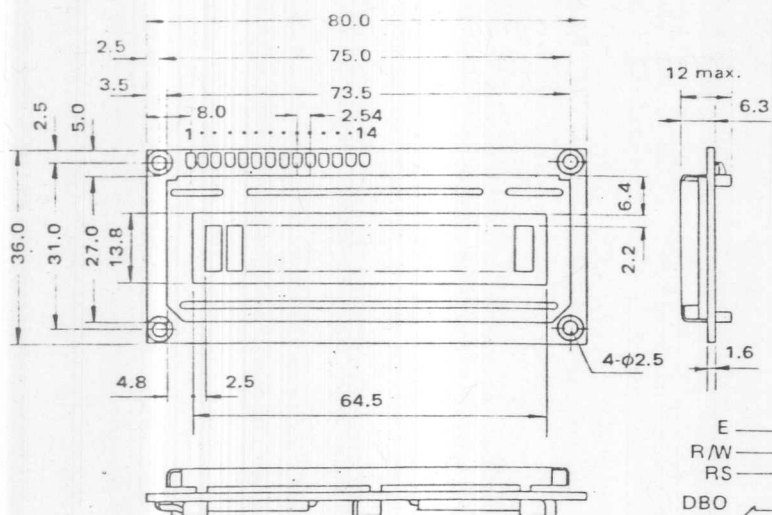


DIMENSIONAL OUTLINE

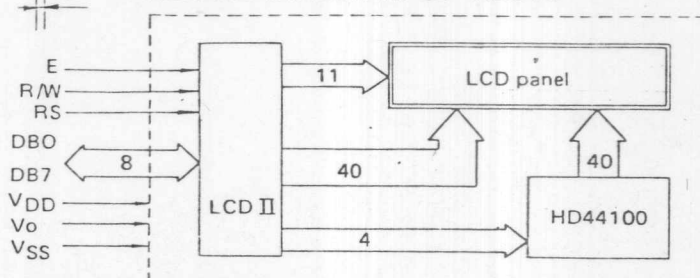
| Item \ Type No. | H2570 | H2571 | H2572 |
|--|-------------------------|-------------------------|-------------------------|
| Number of display character | 16 x 1 line with cursor | 32 x 1 line with cursor | 40 x 1 line with cursor |
| Module size (mm) width x height x thickness | 80 x 36 x 12 | 174.5 x 31.0 x 13.4 | 182 x 33.5 x 13 |
| Effective display area width x height (mm) | 64.5 x 13.8 | 132.5 x 14.0 | 154.4 x 15.8 |
| Weight (g) | 25 | 60 | 65 |

±259.80

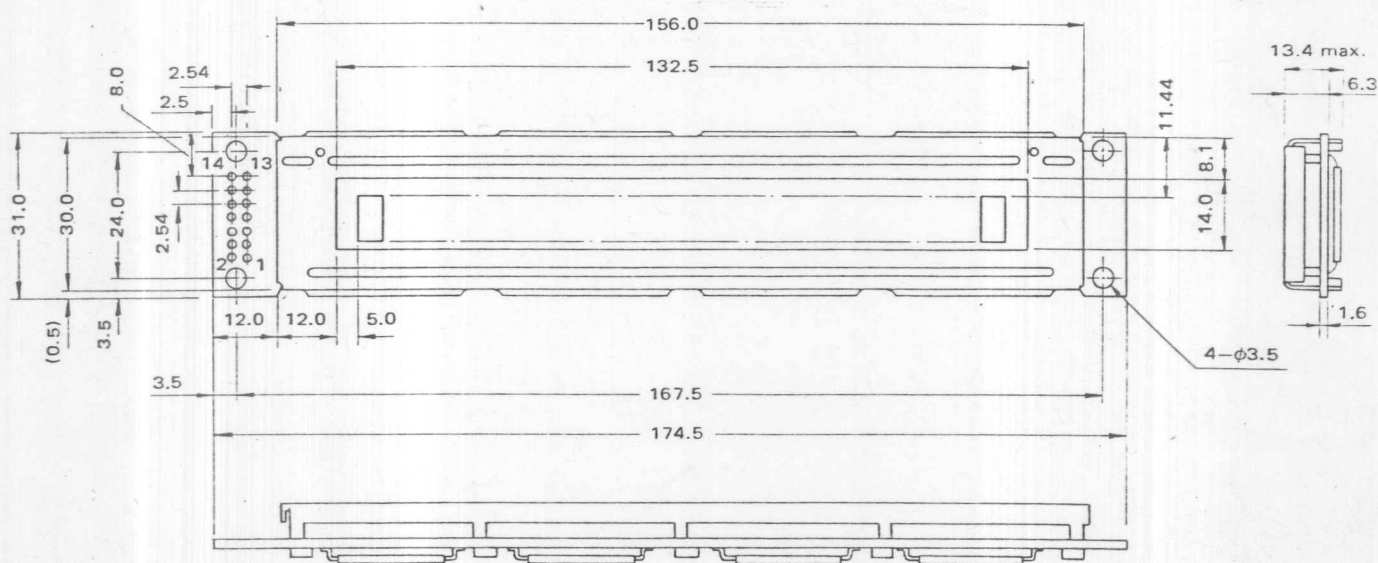
Dimensions in mm.



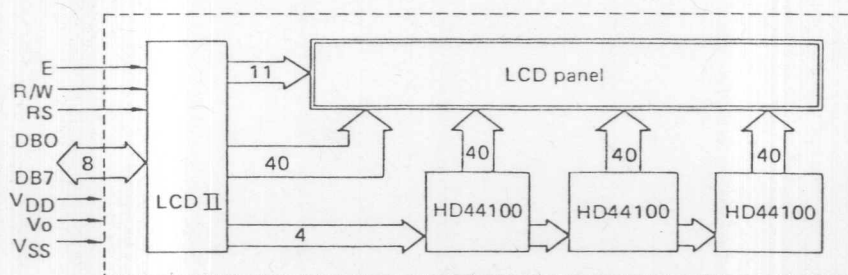
BLOCK DIAGRAM OF H2570



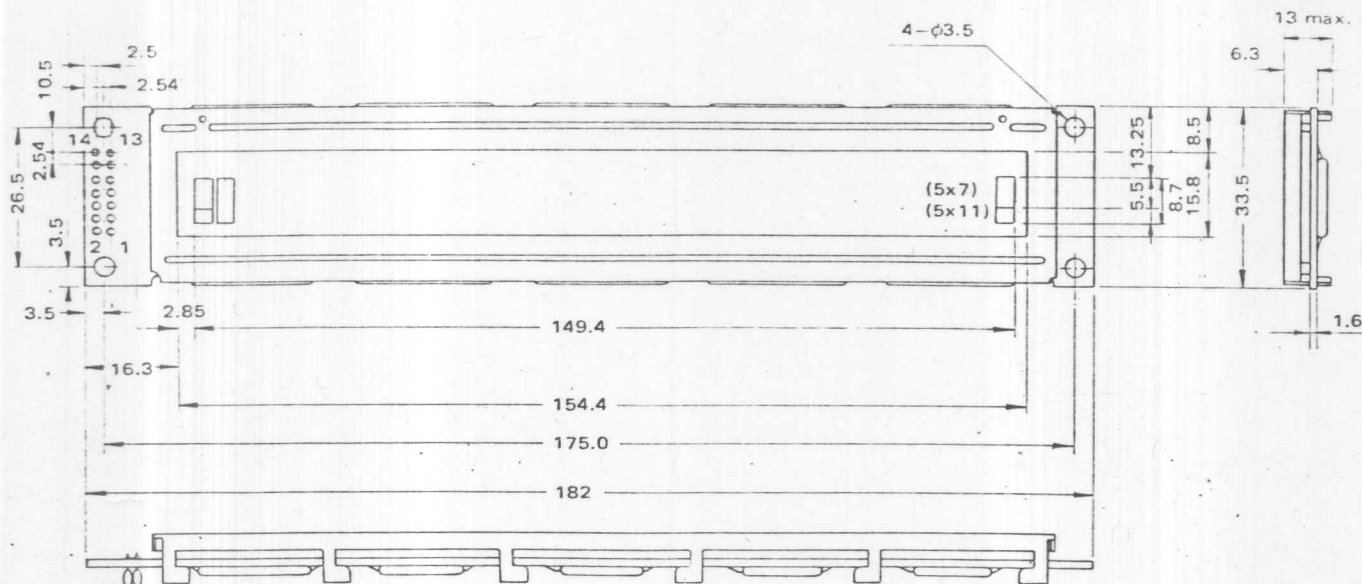
Dimensions in mm.



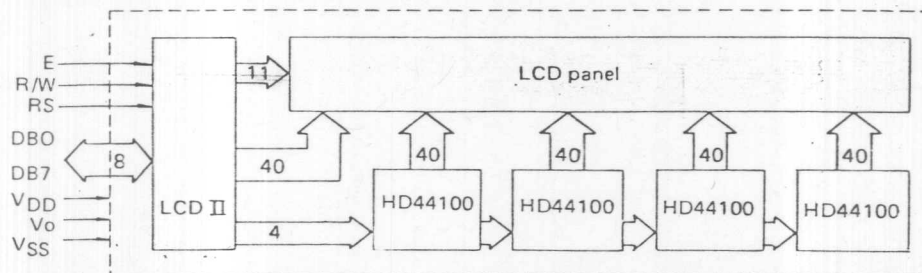
BLOCK DIAGRAM OF H2571



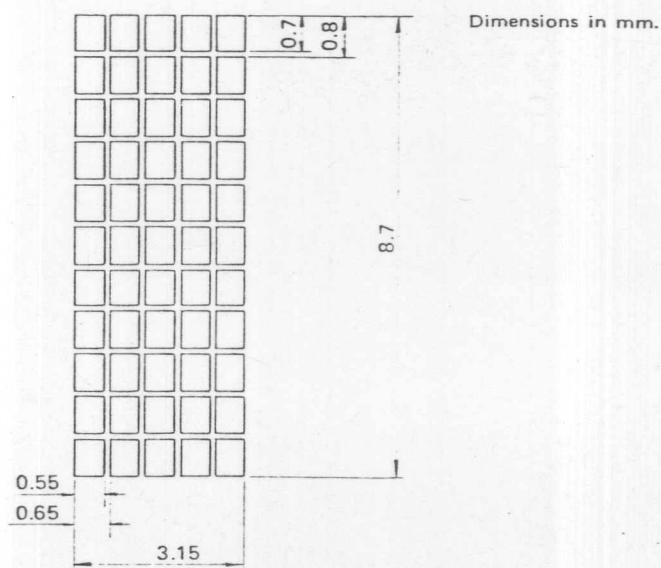
Dimensions in mm.



BLOCK DIAGRAM OF H2572



DETAILED DRAWINGS OF MATRIX PATTERN OF H2570, H2571 and H2572



INTERFACE PIN CONNECTION

| Pin No. | Symbol | Level | Function | |
|---------|-----------------|--------|---|--------------|
| 1 | V _{SS} | — | 0V | Power supply |
| 2 | V _{DD} | — | 5V | |
| 3 | V ₀ | — | — | |
| 4 | RS | H/L | L: Instruction code input H: Data input | |
| 5 | R/W | H/L | H: Data read (LCD module→MPU) L: Data write (LCD module←MPU) | |
| 6 | E | H, H→L | Enable signal | |
| 7 | DB0 | H/L | Data bus line Note (1), Note (2) | |
| 8 | DB1 | H/L | | |
| 9 | DB2 | H/L | | |
| 10 | DB3 | H/L | | |
| 11 | DB4 | H/L | | |
| 12 | DB5 | H/L | | |
| 13 | DB6 | H/L | | |
| 14 | DB7 | H/L | | |

Note:

In the HD44780, the data can be sent in either 4-bit 2-operation or 8-bit 1-operation so that it can interface to both 4 and 8 bit MPU's.

- (1) When interface data is 4 bits long, data is transferred using only 4 buses of $DB_4 \sim DB_7$ and $DB_0 \sim DB_3$ are not used. Data transfer between the HD44780 and the MPU completes when 4-bit data is transferred twice. Data of the higher order 4 bits (contents of $DB_4 \sim DB_7$ when interface data is 8 bits long) is transferred first and then lower order 4 bits (contents of $DB_0 \sim DB_3$ when interface data is 8 bits long).
- (2) When interface data is 8 bits long, data is transferred using 8 data buses of $DB_0 \sim DB_7$.

INSTRUCTIONS

| Instruction | Code | | | | | | | | | | Description | Execution time (when fcp or fosc is 250 KHz) | |
|----------------------------|--|-----|------------|-----------------|-----------------|-----|-----|-----|------------------------------------|---|--|---|------------|
| | RS | R/W | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 | | | |
| Clear display | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | Clears all display and returns the cursor to the home position (Address 0). | 82 μ s ~ 1.64 ms | |
| Return home | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | * | Returns the cursor to the home position (Address 0). Also returns the display being shifted to the original position. DD RAM contents remain unchanged. | 40 μ s ~ 1.6 ms | |
| Entry mode set | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | I/D | S | Sets the cursor move direction and specifies or not to shift the display. These operations are performed during data write and read. | 40 μ s |
| Display ON/OFF control | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | D | C | B | Sets ON/OFF of all display (D), cursor ON/OFF (C), and blink of cursor position character (B). | 40 μ s |
| Cursor of display shift | 0 | 0 | 0 | 0 | 0 | 1 | S/C | R/L | * | * | Moves the cursor and shifts the display without changing DD RAM contents | 40 μ s | |
| Function set | 0 | 0 | 0 | 0 | 1 | DL | N | F | * | * | Sets interface data length (DL) number of display lines (L) and character font (F). | 40 μ s | |
| Set CG RAM address | 0 | 0 | 0 | 1 | A _{CG} | | | | | | Sets the CG RAM address. CG RAM data is sent and received after this setting. | 40 μ s | |
| Set DD RAM address | 0 | 0 | 1 | A _{DD} | | | | | | Sets the DD RAM address. DD RAM data is sent and received after this setting. | 40 μ s | | |
| Read busy flag & address | 0 | 1 | BF | AC | | | | | | Reads Busy flag (BF) indicating internal operation is being performed and reads address counter contents. | 40 μ s | | |
| Write data to CG or DD RAM | 1 | 0 | Write Data | | | | | | Writes data into DD RAM or CG RAM. | 40 μ s | | | |
| Read data to CG or DD RAM | 1 | 1 | Read Data | | | | | | Reads data from DD RAM or CG RAM. | 40 μ s | | | |
| | I/D = 1: Increment I/D = 0: Decrement S = 1: Accompanies display shift. S/C = 1: Display shift S/C = 0: Cursor move R/L = 1: Shift to the right. R/L = 0: Shift to the left. DL = 1: 8 bits DL = 0: 4 bits N = 1: 2 lines N = 0: 1 line F = 1: 5 x 10 dots F = 0: 5 x 7 dots BF = 1: Internally operating BF = 0: Can accept instruction | | | | | | | | | | DD RAM: Display data RAM CG RAM: Character generator RAM A _{CG} : CG RAM address A _{DD} : DD RAM address Corresponds to cursor address. AC: Address counter used for both of DD and CG RAM address. | Execution time changes when frequency changes. (Example) When fcp or fosc is 270 KHz: $40 \mu\text{s} \times \frac{250}{270} = 37 \mu\text{s}$ | |

*Don't care

For details, refer to "HITACHI MICROCOMPUTER SYSTEM: DOT MATRIX LIQUID CRYSTAL DISPLAY CONTROLLER & DRIVER LCD-II (HD44780) USER'S MANUAL".



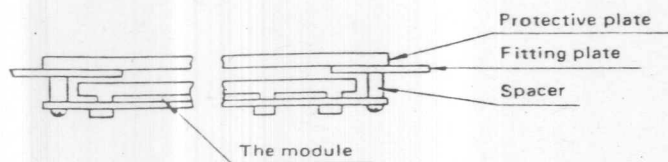
FONT TABLE

| Higher Lower: 4bit 4bit | 0000 | 0010 | 0011 | 0100 | 0101 | 0110 | 0111 | 1010 | 1011 | 1100 | 1101 | 1110 | 1111 |
|-------------------------------|------------------|------|------|------|------|------|------|------|------|------|------|------|------|
| xxxx0000 | CG RAM (1) | | 0 | a | P | ` | P | | - | 3 | E | e | p |
| xxxx0001 | (2) | ! | 1 | A | Q | a | q | , | 7 | 7 | 4 | a | q |
| xxxx0010 | (3) | " | 2 | B | R | b | r | " | 4 | U | x | p | @ |
| xxxx0011 | (4) | # | 3 | O | S | c | s | , | 0 | t | e | e | ~ |
| xxxx0100 | (5) | \$ | 4 | D | T | d | t | , | 1 | t | p | p | @ |
| xxxx0101 | (6) | % | 5 | E | U | e | u | = | * | + | 1 | e | o |
| xxxx0110 | (7) | & | 6 | F | V | f | v | 7 | + | + | 2 | p | z |
| xxxx0111 | (8) | ' | 7 | G | W | g | w | 7 | + | + | 3 | g | x |
| xxxx1000 | (1) | (| 8 | H | X | h | x | 4 | 0 | * | U | r | x |
| xxxx1001 | (2) |) | 9 | I | Y | i | y | @ | 7 | U | U | ' | y |
| xxxx1010 | (3) | * | : | J | Z | j | z | ~ | 3 | n | v | j | 7 |
| xxxx1011 | (4) | + | : | K | L | k | l | (| * | U | E | o | 7 |
| xxxx1100 | (5) | , | < | L | * | 1 | 1 | + | 3 | 7 | 7 | o | m |
| xxxx1101 | (6) | - | = | N | J | n |) | 2 | z | \ | o | t | ÷ |
| xxxx1110 | (7) | . | > | N | ^ | n | + | 3 | E | o | 7 | 7 | |
| xxxx1111 | (8) | / | ? | O | _ | o | + | u | U | 7 | 7 | o | |

PRECAUTIONS IN DESIGN

1. Mounting method

Since H2570, H2571 and H2572 are so constructed as to be fixed by utilizing fitting holes in the printed circuit board as shown below, it is necessary to take consideration the following items on attachment to a frame.



Example of mounting

- (1) Use of a protective plate, made of an acrylic plate, etc. in order to protect a polarizer and LC cell.
- (2) To prevent the module cover from being pressed, the spacers between the module and the fitting plates should be longer than 5.5 in mm.

2. LC driving voltage (V_o) and viewing angle range

Setting V_o out of the recommended condition will be a cause for a change of viewing angle range.

3. Caution against static charge

As this module is provided with C-MOS LSI, the care to take such a precaution as to grounding the operator's body is required when handling it.